Apollo 3000

Set-up, Installation & Parts Manual



Safety Operation

In case of damage to your Dispenser or Pump, which creates a safety hazard the following procedures **Must** be followed.

A Turn Off Pump at Console then....

Isolate power to the Dispenser or Pump.

Using the remote control switch located on the main electrical supply board.

Lock switch if lock mechanism provided, or take measures to ensure isolator will not be turned on prior to the safety hazard being rectified

Isolate power to the Submersible Turbine Pump

by the remote control switch located on the main electrical supply board.

Lock switch if lock mechanism provided, or take measures to ensure isolator will not be turned on prior to the safety hazard being rectified

Note: The isolation of the Submersible Turbine Pump could affect other dispenser on the forecourt.

Call your site manager or company representative immediately for further information.

B Do Not Apply power to the Dispenser without a full service inspection.

If there is a fire or injury, call : Emergency Services.

Caution

Should the word "**FLUId**" appear in Display immediately implement part A & B of this section Refer page 06 of this Manual <u>Apollo 3000 Set Up Procedure Std. Fuel</u> paragraph 06 for details

Caution

This equipment contains components that can be damaged by Electrostatic Discharge. Should you ever need to service this equipment, you must follow full anti-static precautions. Prior to servicing, earth all equipment and wear an anti-static strap. Component must be transported in anti-static material.

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Contents

	Safety Operations	
Page 1	Contents	
Page 2	Stage 1 Under Ground Sump Enclosure Installation.	
Page 3 - 4	Stage 2 Vertical Delivery Pipe Assy Installation	
Page 4	Stage 3 Vent Box Assy Installation.	
Page 5	Stage 5 Modules & Delivery Pipe Assy Installation.	
Page 6 - 7	Apollo 3000 Set Up Procedure Standard Fuel	
Page 8	Pump Stack Test Spec.	
Page 9	Feed Line Details	
Page 10	Rear Grade ID Spec.	
Page 11	Float Switch	
Page 12	Head Cable Entry	
Page 13	Head Cabinet Rear Display	
Page 14	Head Cabinet Assy Inside View	
Page 15	Head Cabinet Front Displays	
Page 16	Head Cabinet Internal	
Page 17	Logic Box (Cabling/Hoses)	
Page 18	Inside Enclosure Layout	
Page 19	Apollo Sump & Module Assy Layout	
Page 20	Vertical Pipe/Vent Box Assy	
Page 21	Fig 1 Sump Position	
Page 22	Fig 2 Sump/Column Position	
Page 23	Fig 3 Service Area	
Page 24	Fig 4 Mounting Positions	
Page 25	Fig 5 Vent Box Position & Sealing	
Page 26	Fig 6 Safety Hose Position	
Page 27	Apollo 3000 Hydraulic & Intrinsic Connections New Zealand	
Page 28	Apollo 3000 Hydraulic & Intrinsic Connections Australia.	
Page 29	Mains Wiring Connections AC Control & Power Supply	
Page 30	Logic Box Connections	
Page 31	Dip Switch Setting/Location	
Page 32	Main Processor lay out Circuit	
Page 33	Apollo 3000 Display Layout	
Page 34	Hose Assy Specifications	
Page 35 – 40	Error Codes	
Page 41	PEC Fuel Pump Fluid/Float Switch Operation in Dispensers	

This is an Interim Manual intended to cover Apollo trial sites, and will be reviewed once trials are complete and design is finalised.

Note also that the Apollo units are based on PEC standards 1000 & 8000 Dispensers and therefore this manual should be used in conjunction with PEC Modular Pumps Installation & Service Manual 87386

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<u>BP Apollo 3000 Dispenser</u> Supply & Installation Procedure

Stage 1 Under Ground Sump Enclosure Installation

Components supplied by PEC to site.

Components include;

Sump Enclosure Box Assy with, Cable Duct, Delivery Ducts with Internal Delivery Pipe Assys. fitted. Bulkhead Seals (Pre fitted into Sump Enclosure) Sump Box Lid with Handles Sump Cover & Sub-frame, Securing Screws & divider skirt fitted Main Wiring Looms & Junction Box (Fitted into Sump Box) Float Switch & Cable Assy (Fitted to Mtg. Brkt.)

Installation Procedure

- Establish proposed/final Forecourt ground level, mark this point on Column.
- Install Sump Box Enclosure into correct position below proposed ground level as shown in figs 1,2 &3
- Ensure Pipe Delivery Ducts protrude 50mm above ground level & 20mm proud of Column. Also ensure top edge of Sump is 60 mm below ground & level. End face of Enclosure is 300 mm out from Column (Fig 1) *Note* Ensure underside of Enclosure is firmly packed to prevent Enclosure sinking or moving.
- Pack filling material around Sump Enclosure approximately up to a point just under Bulkhead Fittings, this is to ensure Enclosure does not move while further work is being conducted.
- Plug or cover Pipe Delivery Ducts to stop any foreign matter entering.
- Install Main Product Feed Lines Into Sump (refer Apollo Hydraulic & Intrinsic Connections Pg. 27 NZ & Pg. 28 Aus.) for correct positioning etc. (Refer page 09 for Feed Line installation Details)
 - T connector terminated with ³/₄" Ball Valve & ³/₄ ³/₄" BSP Elbow

B22 22 12 12

- Ensure Ball Valves Face toward BOTTOM of Sump no more than 10 dec. off Vertical, with lever side towards Column
- Check & tighten all Seals
- Check for Leaks
- Recheck Sump position in relation to Column & Forecourt Surface as per Refer Figs. 1, 2 & 3.
- Secure Pipe Delivery Ducts & Main Feed Lines into position to prevent movement while Back Filling.
- Temporarily pack internal side walls of Sump using timber or similar to eliminate walls collapsing inwards during back filling.
- Install all Servicing Cabling & Pipe work as required for operation. Ensure all services are positioned correctly to clear Vent Box, Head Mtg. & GRP Cladding etc. Ref. fig 2 & 3 for details.
- Recheck Seals & Sump Position.
- Backfill to cover Feed Lines & secure Sump Enclosure position.
- Position & Secure Sump Lid Frame (Centralise around Sump Box) check with Forecourt Level (Note Frame & cover can be raised locally above general Forecourt level if required to prevent water ingress.(Possibly 10 20 mm above general Forecourt level
- Back Fill & Compact to within 150 mm of Forecourt surface, 30 50 mm up Skirting walls
- Concrete Forecourt as per Site requirements.

Stage 2 Vertical Delivery Pipe Assys Installation Procedure

Components Supplied by PEC

Front & Rear Vertical Pipe Assys Head Cabinet Assy. (Fitted with Grade ID Decals) Head Cabinet mtg. Brkts Flexible Safety Hose Assys External Hose Assy, fitted with Nozzles, Grade Covers & Gas Guards Nozzle Grade ID Decals Vent Box Assy Front & Rear (2 x Top Caps) Serial Name Plate. (Name Plate to be Adhered to Top LH corner of GRP head access Door)

• Installation Procedure

• Using a Sprit level find the highest point on Forecourt out to a distance of 160 mm from Main Column(in any direction). Transfer this point onto Front face of Column (Front =Sump @ right hand side of Column) clearly mark as datum point on Column Face. (This is a datum point to start measuring from regards positions of components & mtg. brkts. etc. (See Sketch below) This point must be established to obtain mounting heights & ground clearances etc. for Final Cladding.



- From the above, mentioned Datum Line, transfer & mark a point 2.3 m Vertically up Column. If preferred a second but lower point could be marked @ 1.405m.up Having both these Datum points marked on Column could be advantageous as they could then both serve as a double checks. Note: Marks should be made Horizontally, as they will later be used to align Vertical Pipe & Holster Assy Mtg. Brkts. etc. (Details refer Fig 4)
- Place Front Vertical Pipe Assy 89826 onto front face of Column, top angled section of Pipe Assy. should be pointing out to right hand side. (eg. towards Sump) (*Note: Front of Dispenser = Column on Left with Sump on Right*) Both of the middle two Mounting brkts on Vertical Pipe Assy have a right angle Lug welded to them, these Lugs are location lugs & should be positioned up against right hand face of column.
- With Lugs positioned against Column side face, slide Pipe Assy up until top face of second horizontal Brkt. up Assy aligns with lower mark 1405.4mm Son Column and/or top face of second horizontal Brkt. down Assy aligns with upper mark on Column. Secure into position with "G" or "F" Clamps. (Or Ratchet Ties)
- Check Column Stops on second & third horizontal brkts are hard against Column Face, also check Vertical Pipe Assy is vertical. (If not this could indicate Column is not truly Vertical, in this instance move either top or bottom of Pipe Assy. to obtain true Vertical reading, secure Clamps, recheck heights from Forecourt datum marks.

- <u>Stage 2 Vertical Delivery Pipe Assys & Modules Installation Procedure Continued</u>
- Drill pilot holes into Column through holes provided in horizontal fixing Brkts. (Min. 2 per Brkt. required) Uses 12 Gauge 32mm (12/24 x 23 Hex Hd. Buildx 500 Series or similar Screw.
- Repeat process on rear side. Ensuring brackets on rear Pipe Assy. are horizontal with front set. Also ensure Column Stops on rear Pipes are positioned exactly in same relationship from Column as per front set.
- Assemble Head Cabinet Mounting Brkts. 89711 (Pg. 20) onto Head Cabinet, over M5 Studs provided in Head Cabinet, Nuts supplied. <u>Note</u>: Cut out section of brkts positioned towards bottom of Cabinet.
- Position lower Head mtg. brkt. onto top face of second horizontal fixing Brkt of Vertical Pipe Assy. Cut out section in lower Head Mtg. Brkt. locates over fixing brkts as mentioned above.(Pg. 21)
- Secure Head into position with Clamps, drill pilot holes & fix with Screw as per Vertical Pipe Assy. (Refer Fig 4
- Attach Logic Box Assy to under side of Head Cabinet Assy. (Studs pre positioned) ,(Pg. 18)

Stage 3 Vent Box Installation

Refer Fig 5 (pg.25) for details. (Dispenser Front shown)

- With top Cap removed insert Vertical Pipes into gap in Body, & manoeuvre Vent Box up behind Vertical Pipe Assy. into position as shown fig 5. Ensuring base edge contacts against Forecourt.
- Place Top Cap into gap of Vent Box as shown in Fig 5 (Ensure Cap is fitting correctly into recess.)
- Cut a 70 mm long section of 50 mm wide Aluminium Adhesive Tape. Fold in half length wise into the non adhesive side (eg. folded along length with adhesive sides exposed to out side & non Adhesive sides touching)
- Place the hinge or folded side of above mentioned tape section up into the inside of vent Box at the junction of the Top Cap and inside wall, equally space length over width of Cap. Manoeuvre tape to adhere to either to top or side wall inner face, then unfold tape section to adhere onto adjacent face also. Press tape into place to seal. Repeat process on opposite side
- Cut a section of tape to the approximately length of the Box Width, adhere this section equally over under side of long joint between Box Body & Top Cap. Shorter pieces could also be applied to under side joints between & on each end of where Vertical Pipes protrude through Assy.(Refer Fig 5)
- Using a Bostik Matrix 600 or 700FC Polyurethane Sealant, Seal all joints as indicated in Fig 5 Ensure a good size Fillet @ intersection of Vent Box to Forecourt.(Note: Ensure inside of Vent Box Assy. is seal sufficiently to eliminate the potential to leak out into the inside of Dispenser Cladding.
- Fit Safety Flex Hose Assys between Delivery Pipe Assys (in Ducting) & Vertical Pipe Assy's. (Fig 6)
- Repeat above process @ Rear side of Dispenser.

Stage 4 Modules & Delivery Pipe Assys Installation Procedure

Components Supplied by PEC

Meter Module Assy. including AC Control Box Assy. (Per Addressed) Module Hinge Pin Product Feed Line Hose Assys. x 3 (Feed Line to Modules) Product Delivery Hose Assys 3 Sets. (Module to Delivery Pipe Assys in Ducts)

Installation Procedure

(Start with Module C closest to Column)

- (Ensure Product Position is Correct (Refer Pg. 27 NZ or 28 Aus.) Apollo 3000 Hydraulic & Intrinsic Connections
- Connect Internal Delivery Hoses to Internal Delivery Pipe Assys (these exit into Sump from Ducts) (Refer Pg18) **Inside Enclosure Layout**
- Attach Internal Product Feed Hose Assys x 3 to Fixed Main Feed Lines through Sump.
- Install Module Assy. "C" fit Hinge Pin lift module & Position Hold Up Brace (Refer Pg. 27 NZ or 28 Aus. to Ensure Correct Feed Path.)
- Attach Feed & Delivery Hoses to Meter Module.
- Repeat previous procedure for Module "B" then Module "A"
- Connect Mains & Switched Phase Cables into AC Control Boxes (Refer Drawing Mains & Switched Active Cabling Layout Pg. 29. Secure Cables into Trunking provided, refer Pg. 18 & 19 (Inspection of Cabling required)
- Assemble Float Switch/Bracket Assy onto Studs provided @ RH. end of Sump Enclosure. Position Float down into Secondary Sump as low as possible. Ensure Float is free to travel upwards without obstructions etc.
- Using a Draw Cord, Pull Encoder, Float Switch & AC Signal Cables through Cable Duct. Also feed Steel Wire Amour Cable up Cable Duct.
- Plug Cables into Logic PCB Assy (see Drawing Control Logic Box Distribution PCB 87111 Pg. 30) (Cables are Marked.)
- Fit Steel Wire Armoured Cable, Mains Feed Line into Head Cabinet via Flp. Gland connect as per Drawing Pg. 29 (inspection of connections required) (Note Glands into Head Cabinet not Supplied)
- Insert Pump & LAN Comm's Cables into Head Cabinet & Connect (through FLP. Glands)
- Pump Comms Refer Pg. 32. Plug LAN Comms. direct to FST unit (Plug Supplied with FST)
- Attach Nozzle Holster Switch Cables to Logic Box (see Drawing Pg.30 + Pg17.)
- Check all Hydraulic & Electrical connections (Electrical connection etc. to be Certified)
- Program Dispenser as per pages 6,7 & 8 (Also refer PEC Modular Pumps Manual 87372)
- External Cladding to be fitted. Refer instructions from FDL (Fibreglass Development Ltd
- <u>Note</u>: External Hoses can be fitted at this stage if required for testing etc. However they will need to be remove to assemble GRP Cladding
- Once Cladding & External Hoses fitted Test run checking for leaks etc. (Use Pump Stack test Pg. 08)
- Check operation of Float Switch by lifting to activate. (if software VA 2.30P or greater fitted, Dispenser will fatal error with **FLUid** showing in Dollar display. **Power down to reset**.(Refer Pg. 6, 7 & 42 for details & explanation)
- Check Cover is replaced over Power Supply PCB.

Apollo 3000 Set Up Procedure Standard Fuel

1. Set He Addresses Die Seritshas				
1. <u>Set Up Addresses Dip Switches</u>				
Set addresses on AC Control PCB as shown in table below				
Note AC Control Boxes number from right to Left as viewed with Column on your left, refer	•			
Apolio 5000 Hydraune & Intrinsie Connections layout Section Pg. 28 & 29				
$\underline{\text{Box no.}}$ $\underline{\text{Dip Switches}}$				
4 3 2 1				
A on on on off				
B on on off off				
C ON ON OII OII				
2. <u>Preset Display PCB Dip Switch Setting</u>				
3 Product front = 3,5 & 12 are on rest are off 2 P $= 1 + 1 + 1 = 10$				
3 Product rear = all set off				
3. <u>Power up</u>				
Apply Power, for Software version $\sqrt{A} 2.21 \approx >$ listen for single deep -pause-single-follow	veu			
Displays should show as follows				
Displays should show as follows $EDONT$ $Dn \land DE \land D$ $Dn \land b$				
FROM FIL- A REAK FIL- 0				
FII FII FII Note if you get FIFL OFF then toggle Managers Switch to get required display				
A Setting Hoses Active				
4. <u>Setting Hoses Active</u> . Empty RAM by Switching managers Switch pressing Service Agent Button enter 10 Fill Fi	(1			
Empty KAM by Switching managers Swit. & pressing Service Agent Button, enter 10-Fill-Fill.				
Activate as follows				
Hose F1 – Enter 22-Fill-1-Fill Hose R1 – Enter 23-Fill-1-Fill				
Hose F^{T} – Enter 42 Fill 1 Fill Hose P^{2} – Enter 43 Fill 1 Fill				
Hose F2 = Enter 62 Fill 1 Fill Hose F2 = Enter 62 Fill 1 Fill				
5 Check Pricing Displays read as indicated on Graphic Panel				
5. Check Filling Displays lead as indicated on Oraphic Failer Cents per Litre = "0.0" for Cents & Dollars per Litre = 0.000 for Dollars				
Pafer PEC Manual 87372 section "Din Switch Sattings Multipee" for corrections				
Set Product Price				
$\frac{\text{Set Froduct Free}}{\text{Product } \Delta = \text{Enter 31-Fill} + \text{smount} (eq.993-Fill = 99.3c)}$				
Product $B = Enter 51_Fill_{$ amount_Fill}$				
Product $C = Enter 71_Fill_$ amount_Fill$				
Note To test Comms And Console control is working correctly enter a non real price for each product				
and then switch unit over to Console control price should then change as set on console. Check bo	th			
sides				
6 Pump Number (Comms, Connection)				
To connect to Console unit has to be numbered both front & rear				
To number Front Enter 20-Fill (Display shows PF-00)				
Enter Required # (Display shows = PF - (number entered)- enter Fill				
To number Rear Enter 21-Fill (Display shows = $PF-00$)				
Enter Required # (Display shows = PF- (number entered)- enter Fill				
Switch Managers Switch to normal				
Note $(\#) = Pump/Console number$				

Apollo 3000 Set Up Procedure Standard Fuel continued

- <u>7</u> Plug in Batteries
- 8 Test Diagnostics (Refer Pg.08)

9 Version VA 2.30P or Greater Software Version VA 2.30P has optional settings between Air Sense & Fluid Float Switch Operation. Explanation of operation:

Air Sense Operation = No Link present or Link Cut @ position 10 @ Dip Switches positioned on Front Preset Display PCB Assy.

Fluid/Float Switch Operation = With Link in place @ position 10 @ Dip Switches positioned on Front Preset Display PCB Assy.. <u>Air Sense Operation</u> This mode allows for Air to be detected when an Air Sense device is fitted. Air Sense operate such that when Air is detected, the Main Valve of the fluid being dispensed will shut down for a period of one Minute, delivering on Final/Slow stage only. Should the Air source not be eliminated within that period of one minute then Pump will shut down completely & display Fatal Error between 32 & 37 depending on product being dispensed (Air Sense operation set with No Link or Link Cut @ position 10)

<u>Fluid/Float Switch operation</u> allow for a Float Switch which is positioned within under ground Sump Enclosure, to detect the presents of Fluid which then shuts Dispenser down. (Reset required)

If Dispenser is in idle stage (eg. Non Delivery) & Float Switch is activated (Fluid detected), FLUId with appear immediately in both Front & Rear Main Displays.

However if one side of Dispenser is operational (delivering) & Float Switch is activated (Fluid detected), Dispenser will shut down immediately with FLUId appearing in opposite side Display to that being used. On the side that was operational, Displays will retain present delivery values but will start to flash once Nozzle has been returned to Holster for a period of 1 minute. FLUId will appear in that side Display only once Nozzle has been removed.

Power should be immediately shut off to Dispenser.

<u>To reset Dispenser :</u> Remove fluid from Sump Enclosure, repair source of Fluid leak , ensure Float Switch is returned to normal operating position. Return Power to Dispenser, operation should commence as normal.

Note To switch Dispenser to LOCAL mode (Non Console control)

With Managers Switch on Enter 04-Fill middle display shows LOCAL enter Fill again, Switch Managers Switch to normal.

(Note Comms Cable must be disconnected for Local mode to operate)

Pump stack test 30* 50* 70* 30*

This test cheeks the operation of the pump motors (internal or submersible). The motor can be switched on and off, as can the slow and fast flow rates. The flow rate is displayed in the *Price per litre* display.

Pump motor Function number

F1 & R1	- 30
F2 & R2	50

F3 & R3 70

Initially, the display appears as shown in the illustration. Decimal points between each set of two figures indicate whether nozzles switches are open. A central decimal point indicates air in the flow detected by the air sensor (if installed). The first digit gives the rate of flow for the hose, in tens of litres per minute, and the second digit counts the number of encoder errors received.



Note Encoder errors can be any number but must not change (eg change indicates error)

Diagnostic Testing of Motor & Valve Operation

This function can be used to turn Motor, Final & main stages of Solenoid valves idea for checking connection and correct operation etc.

Note Managers Switch must be on to access these functions & Diagnostic Switch pressed

Function 30 for Product 'A'

Function 50 for Product 'B'

Function 70 for Product 'C'

Once in any of the above Function press key once as listed below to activate and a second time to deactivate. Note Numbers being activated show in 'Dollars Display"

Key Function

1 Motor

2 Sol/Valve final stage (front)

3 Sol/Valve main stage (front)

4 Sol/Valve final stage (rear)

5 Sol/Valve main stage (rear)

Feed Line Detail



Note distance between test point seals on assy. shown above must be min possible . Inside distance between Bulkhead Seals in Hydraulic Enclosure is, 0.432m therefore feed line Tee termination arrangement must fit within this distance.



Above view is as viewed from enclosure (sump) end away from Column (RH end). Tee & Shut off Valve hang down towards floor of enclosure with ³/₄ Elbow facing to back face of enclosure. Handle of shutoff valve operates in the same plan as feed line, (eg front to rear.

Rear Grade ID



Float Switch





Head Cabinet Rear Display



Head Cabinet Inside View



Head Cabinet Front Displays



Head Cabinet Internal



Logic Box



Inside Enclosure Layout



Rerfer Pg. 27 & 28 For Hydraulic Layout Refer Pg.34- For Hose Specs.





Delivery Hose Lengths

89744 A/F&R = ³/₄ Hose @ 1.67m - ³/₄ Swivel Nut 19243/12/12/AU - F/Swivel 90 Elbow 1B243-12-12 89743 B/F&R = ³/₄ Hose @ 1.39m - ³/₄ Swivel Nut 19243/12/12/AU - F/Swivel 90 Elbow 1B243-12-12 89742 C/F&R = ³/₄ Hose @ 0.9m - ³/₄ Swivel Nut 19243/12/12/AU - F/Swivel 90 Elbow 1B243-12-12

Internal Supply Hose Lengths

89748 ³/₄ Hose @ 1.05m - ³/₄ Swivel Nut 19243/12/12/AU (x3)

<u>Pipe Assys are as follows:</u>

"A" = 89794 Internal Pipe Assy Upper

- "B" = 89796 Internal Pipe Assy Middle
- "C" = 89798 Internal Pipe Assy Lower

Note These Pipe Assys run up inside Ducting to connect to Vertical Pipe Assys attached to Column.



Stage 1 Installation Procedure **Sump Position**

Fig 1 Under Ground Front View Apollo Sump



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Stage 1 Installation Procedure <u>Sump/Column Position</u>



²²

Stage 1 Installation Service Area Spec.



Stage 1 Installation Procedure <u>Mounting Positions</u>



Stage 3 Vent Box Installation Vent Box Position & Sealing Spec.



Stage 3 Vent Box Installation <u>Safety Hose Position</u>.



Apollo 3000 Hydraulic & Intrinsic Connections New Zealand

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Apollo 3000 Hydraulic & Intrinsic Connections Australia

GME 01/11/00 Updated 27/11/00-21/08/01-27/02/02 File @ GME c:/mydrawdt/apollo/lay-3000.idw apollo 3000 Aus Pg. 1







Display Dip Switch Location <u>on</u> Front Preset Display PCB Assy

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Main Processor Board Information & Connections Part Number 87101

The main Processor Board controls all Pump operations, either alone or together with an input Processor Board The basic elements are :

80c31 or 80c32 Processor 64K external program Memory (Eprom) 32K Static Ram (Battery backed 2692 DUART Encoder Interface Power Control Display I/O Interface External / Internal program Selection Diagnostic communications AC Control Pump Communications Interface Auxiliary I/O



Main processor connections


Apollo 3000 Display Layout

5/8" Hose Assy fitted with @ Nozzle ES-Break





5/8" External Hose Assy Specifications (Original fitted with Inline Dry-Break)

Note: Above Bry Break 1 per each external hose: 5/8 ID Hose @ 250 mm 7/8 SAE Sw/Nut (824170) - 3/4 BSPP Fittings Hose Assy "A" : 5/8 ID Hose @ 3.4 m 3/4 BSPP (01805) - 3/4 BSP Female (01803) Fittings. Assy PEC Pt. # 89885 Hose Assy "B": 5/8 ID Hose @ 3.25 m 3/4 BSPP (01805) - 3/4 BSP Female (01803) Fittings. Assy PEC Pt. # 89884 Hose Assy "C": 5/8 ID Hose @ 3.025 m 3/4 BSPP (01805) - 3/4 BSP Female (01803) Fittings. Assy PEC Pt. # 89883

Internal Hose Assy Specifications 3000

Product Delivery Hose Assy - 3/4 ID Hose - 3/4 Female Swivel Nut 19243/12/12/AU & 3/4 F/Swivel 90 Elbow 1B243-12-12 Hose cut as below

"A" Module : Pt. # 89744 @ 1.67 m x 2

"B" Module : Pt. # 89743 @ 1.39 m x 2

"C" Module : Pt. # 89742 @ 0.9 m x 2

Internal Feed Supply Hose Assy Specifications 3000

Product Feed Hose Assy: - 3/4 ID Hose @ 1.05 m - 3/4 Female Sw/Nut both ends (3 per unit) (Feed Line to Modules)

PEC Pt. # 89748



Safety Flex Hose Assy Specifications 3000

Safety Flex Hose Assy: - 3/4 ID Hose @ 150 mm - 3/4 Female Sw/Nut both ends (6 per unit) (Feed Line to Modules)

PEC Pt. # 89846

Errors

This chapter contains the full list of error codes, in numerical order.

Errors are normally indicated by the error code (number) being displayed. The error is displayed as **ERRxx**, where **xx** is the code number. Errors are also written to an error log. You can check logged errors using Function 02 as detailed in chapter 4.

Startup System Errors

Error codes (01..09) are reserved for startup errors. This type of error is detected before the displays are initialised, and is reported using beep codes (pump beeps once for error 01, twice for error 02, etc.) Some of these codes can also be dynamically checked during normal operation, in which case they will be reported in the normal way (i.e., they will display the **ERR xx** message and stop all deliveries). These errors are fatal errors (processor halted) and require the pump to be reset. Power down and wait for 5 seconds before switching on the pump.

00 Start up log

This is not really an error it contains the number of startups.

01 Processor Error

This is a sequential IRAM address test which is performed at startup. It tests the processor's 4 register banks, and halts the processor if an error is found. This check is performed in the **init** module.

02 Internal Ram error

Error 02 is a sequential IRAM address test which is performed at startup. It covers all IRAM excluding the 4 register banks, and halts the processor if an error is found. This check is performed in the **init** module.

03 Eprom Error

Error 03 indicates a checksum error. This may occur either at startup or dynamically during operation. In either case the processor is halted if an error is found.

04 External RAM Error

This is a walking bit test of the XRAM. This test is performed both at startup (entire XRAM checked) and dynamically (one address per call from main loop). In either case the processor is halted if an error is found.

05 Non Volatile Setup

Error 05 is a check of the non volatile variables. These are the set up variables which must remain unchanged during a power failure. They remain constant unless changed by a diagnostic function. They are checked (against their backup variables) both at startup (all non-vol variables checked) and dynamically (one byte checked each call from main loop). If an error is found, the non volatile variables are all reset to their default values and (if not found during startup) the system restarts.

06 Delivery variables lost

This is a startup check of the current/last delivery related variables. These variables are overwritten with each new delivery, but in case of power loss, must be present between deliveries. Unlike the non-vol variables, during deliveries, these are continually changing and are therefore not checked dynamically. At startup, these are checked (for corruption of XRAM during power loss) against their backup variables. If an error is found, the non volatile variables are all reset to their default values.

07 Keyboard Error

This is a startup check of local or remote (input processor) DIP switch setting validity, and for the presence of the relevant keyboards. This error is non-fatal error which serves as an audible warning to reconfigure DIP switches or replace keyboards and restart the system.

Errors 08 and 09 are reserved.

Fatal Errors (excluding fatal startup errors)

		Errors 10 through to 29 all cause the processor to stop. The errors are displayed but beeps are not sounded. The pump must be reset after one of these errors.
1015	Pump Control S	State Errors (Pump AF)
16	Stack Error	This indicates an attempt to enter an undefined side control state on a particular pump number.
		The stack is continuously checked. If a stack overflow occurs, error 16 will be displayed. This check is performed in the dynchk module.
17 Di	isplay Error	
40	Variable Dange	If a Display error is indicated, a translation error occurred when writing to one of the 7 segment LCD displays.
10	Variable Range	Error 18 indicates a global software parameter (ie pump, grade or price etc) is not within its normal range. This can be a result of corruption of the internal data RAM, which may cause unpredictable results. This check is not limited to any particular module, but is used by any procedure that requires range checking
19	Dollar Maths Er	ror
		At the end of a delivery, the delivery dollar calculations are performed (ie price per litre multiplied by litres equals dollars). Error 19 indicates an error occurred in the calculations. A likely cause for this would be a price change (or corruption of the price variable) during a delivery.
20	Litres Maths Er	ror
		At the end of a delivery, the delivery quantity accumulation calculation is made (ie, total number of encoder counts for the delivery time multiplied by the encoder constant equals the litres displayed). Error 20 indicates an error occurred in the accumulation. If this is not the case, it is probable that the encoder is going too fast, such that the incoming encoder counts (which are accumulated under interrupt control) are not being "consumed" quickly enough by the maths routines to prevent a rollover.
21	Clock Error	
22	Motor Control (A Clock Error indicates that the current time variable (which is used to time tag events) is not incrementing.
22	Motor Control E	Error 22 indicates that an attempt was made to turn a motor on or off when it was already in that state (according to the software)
23	Solenoid Contr	ol Error
		This indicates that an attempt was made to open or close a solenoid valve when it was already in that state (according to the software). It will also occur (except in diagnostic mode) if an attempt is made to turn on a solenoid valve when the corresponding motor is not on.
24	Power Fail	
		This error indicates the system entered its main initialisation procedure (which should only happen on power up or as a result of certain diagnostic functions), but the power fail flag does not show power failed. This may occur in the event of a total power loss (including the lithium battery) such that the XRAM
0 5		was corrupted, or if the power fail procedures are not functioning correctly.
25	Input Processo	r to main failure
26	Main to Input P	This error will occur if the system expects an Input Processor to be present (i.e., it was auto-detected at power up) but is no longer receiving any comms response from it. This would be caused by either a fatal error in the input processor, or a physical loss of connection on the serial link between the two processor boards.
-		This error will occur if the system expects an Input Processor to be present (i.e., it was auto-detected at power up) and is receiving comms response from it, but the Input Processor is not receiving data from the main processor.

This would be caused by either a fatal error in the input processor, or a physical loss of connection on the serial link between the two processor boards.

27 Remote Parameters Failure

Error 27 will be displayed if the pump is not within the diagnostics functions and the remote rx_param block that was sent from the input microprocessor is different to the set stored by the you.

28 Display pointers corrupted

A constant check is dynamically made, of the display information. This error indicates an error has occurred which could cause incorrect information to be displayed on the LCDs.

29 Not used

33

36

These error codes are reserved.

Single Pump Number Fatal Errors

Errors 30 through to 59 do not cause a complete system crash, as they relate to a single pump number only. They cause the related pump to stop delivery, and its displays to flash. This continues until the nozzle is replaced and any nozzle on that pump number is removed again. The **ERRxx** message is then displayed on that pump number and all further processing of the pump ceases.

Note that all other pump numbers can continue unaffected. To use the affected pump again, the pump unit must be reset (powered off for at least 5 seconds).

30 LPG Temperature Probe 1 Error

This is caused by either an open circuit, short circuit or out of range error being detected on probe 1 by the input processor. This error is fatal only to the pump numbers associated with the LPG grade.

31 LPG Temperature Probe 2 Error

Error 31 is caused by either an open circuit, short circuit or out of range error being detected on probe 2 by the input processor. This error is fatal only to the pump numbers associated with the LPG grade.

<u>Note</u> Errors 32 – 37 apply to units fitted with software version lower than va 2.30p only

Units fitted with Software va 2.30p & greater & Float Switches fitted, Fatal Error as FLUId Ref. Pg 41

32	Grade 1 Front hose Detected Fluid Present bottom of Hydraulic Sump Enclosure
	(Pump A1)

During a Grade 1 delivery, Float was activated for more than 1 minute.

Grade 1 Rear hose Detected Fluid Present bottom of Hydraulic Sump Enclosure (Pump B1)

During a Grade 1 delivery, Float was activated for more than 1 minute

34 Grade 2 Front hose Detected Fluid Present bottom of Hydraulic Sump Enclosure (Pump C2)

During a Grade 2 delivery, Float was activated for more than 1 minute.

35 Grade 2 Rear hose Detected Fluid Present bottom of Hydraulic Sump Enclosure (Pump D2)

During a Grade 2 delivery, Float was activated for more than 1 minute.

Grade 3 Front hose Detected Fluid Present bottom of Hydraulic Sump Enclosure (Pump E3)

During a Grade 3 delivery, Float was activated for more than 1 minute

37 Grade 3 Rear hose Detected Fluid Present bottom of Hydraulic Sump Enclosure (Pump F3)

During a Grade 3 delivery, Float was activated for more than 1 minute

38 Grade 1 Front encoder error

(Pump A1)

Grade 1 front encoder inputs out of sequence for more than 1 count in 512 (0.19% minimum error rate). This could be due to the encoder missing a count, the rotation being backwards, etc.

39 Grade 1 Rear encoder error (Pump B1)

The Grade 1 rear encoder inputs were out of sequence.

40 Grade 2 Front encoder error

(Pump C2)

Grade 2 front encoder inputs out of sequence for more than 1 count in 512 (0.19% minimum error rate). This could be due to the encoder missing a count, the rotation being backwards, etc.

41 Grade 2 Rear encoder error

	(Pump D2)	
	Th	e Grade 2 rear encoder inputs were out of sequence.
42	Grade 3 Front enco	oder error
	(Pump E3)	
40	Th	e Grade 3 front encoder inputs were out of sequence.
43	Grade 3 Rear enco	der error
	(rump רט) דע	a Grada 2 roor anadar inputs ware out of sequence
44	Grade 1 Front enco	oder too fast
	(Pump A1)	
	Th	is error indicates an overflow of either encoder counts or encoder errors was detected for the Grade
	1 f	ront encoder.
45	Grade 1 Rear enco	der too fast
	(Pump B1)	
	Th	ere was an overflow of either encoder counts or encoder errors detected for the Grade 1 rear
46	ence Grado 2 Eront once	coder.
40	(Pump C2)	
	(1 4 p 0 _) Th	ere was an overflow of either encoder counts or encoder errors detected for the Grade 2 front
	ene	coder.
47	Grade 2 Rear enco	der too fast
	(Pump D2)	
	Th	ere was an overflow of either encoder counts or encoder errors detected for the Grade 2 rear
10	ence Grado 3 Eront ana	coder.
40	(Pump E3)	
	(: •p _•) Th	ere was an overflow of either encoder counts or encoder errors detected for the Grade 3 front
	ene	coder.
49	Grade 3 Rear enco	der too fast
	(Pump F3)	
	Th	ere was an overflow of either encoder counts or encoder errors detected for the Grade 3 rear
50	Grade 1 Front enco	coder. Oder run on
50	(Pump A1)	
	Flo	by did not stop (the encoder was still rotating) at the end of a Grade 1 front hose delivery (i.e. after
	the	; "get dribble" state has timed out).
- 4	Po	ssible fault could be leaking valves.
51	Grade 1 Rear enco	der run on
	(Fullip BT)	ow did not stop (the anoder was still rotating) at the and of a Grade 1 rear base delivery
52	Grade 2 Front enco	oder run on
	(Pump C2)	
	Flo	ow did not stop (the encoder was still rotating) at the end of a Grade 2 front hose delivery.
53	Grade 2 Rear enco	der run on
	(Pump D2)	
	Flo	by did not stop (the encoder was still rotating) at the end of a Grade 2 rear hose delivery.
54	Grade 3 Front enco	oder run on
	(Pump E3)	
55	Grade 3 Rear enco	der run on
55	(Pump F3)	
	(i chilp i c)	ow did not stop (the encoder was still rotating) at the end of a Grade 3 rear hose delivery.
56	LPG Overspeed	$\Gamma_{\rm r}$ and $\Gamma_{\rm r}$ (see encoder that sum rounding) at the end of a state s rout hose derivery.
	Flo	ow rate detected during delivery exceeded overspeed trip setting. Note that this error on one LPG
	pu	mp will display on both, regardless of whether the other is delivering or not.
	Loss of encoder co	onstant or LPG specific gravity setting

One of these values is corrupt, and has not yet been set back to a valid value (using the appropriate diagnostic function).

58 LPG Sensor failure

The LPG sensor has stopped providing or is providing incorrect information, to the input processor.

59 LPG system vapour present

During an LPG delivery vapour was sensed in the system for more than one minute.

Non Fatal System Errors

Errors 60 through to 89 do not cause any loss of system functionality. They are logged only (for service use).

Comms Channel A errors

60	Channel A Receiver Parity Error
61	This indicates a parity error was detected in one or more of the received message bytes. Channel A Receiver Framing Error
62	Character was received for which no stop bit was detected. Channel A Receiver Break Error
	A steady low (space) signal has appeared at a receiver, indicating a break condition at the transmitting end, causing this error code. The formal definition is that an all zero character with no stop bit has been received.
63	Channel A Receiver Overrun Error
~ /	This indicates an overflow of the 3 byte FIFO buffer for a receiving channel. This means that the processor is not reading the incoming data fast enough to prevent overwriting this stack.
64	
65	Channel A Receiver Data Error
	Error 65 indicates the polling message received from the Console is an invalid type, i.e., a new feature has been added to a console which is not yet supported, or the comms line has been corrupted (in which case a checksum error will probably also occur).
66	Channel A Receiver Overflow Error
67	The message received was too long for the buffer, causing this error. This may happen if no EOM character or sequence is detected.
07	The transmitter has tried to send a message which is too long. This means that the transmit huffer's last
68	position was reached, but an EOM character or sequence was not present. Channel A Receive Timeout Error
	This indicates that the receiver is expecting a character from the Console, but has not received one for more than 1 second.
69	Channel A Transmit Timeout Error
	This timeout error indicates that the transmitter is attempting to send a message to the Console, but there has been a delay of more than 1 second since the last character was transmitted.
Con	nms Channel B errors
70	Channel B Receiver Parity Error
71	Error 70 indicates a parity error was detected in one or more of the received message bytes. Channel B Receiver Framing Error
72	A character was received for which no stop bit was detected. Channel B Receiver Break Error
	A steady low (space) signal has appeared at a receiver, indicating a break condition at the transmitting end. The formal definition is that an all zero character with no stop bit has been received.
73	Channel B Receiver Overrun Error
	This indicates an overflow of the 3 byte FIFO buffer for a receiving channel. This means that the processor is not reading the incoming data fast enough to prevent overwriting this stack.

74 Channel B Receiver Checksum Error

The message received had a checksum error.

75 Channel B Receiver Data Error

This indicates that the polling message received from the Input Processor is an invalid type (or that the comms line has been corrupted, in which case a checksum error will probably also occur).

76 Channel B Receiver Overflow Error

The message received was too long for the buffer. This may happen if no EOM character or sequence is detected.

77 Channel B Transmitter Overflow Error

The transmitter has tried to send a message which is too long. This means that the transmit buffer's last position was reached, but an EOM character or sequence was not present.

78 Channel B Receive Timeout Error

This indicates that the receiver is expecting a character from the Input Processor, but has not received one for more than 1 second.

79 Channel B Transmit Timeout Error

This indicates that the transmitter is attempting to send a message to the Input Processor, but there has been a delay of greater than 1 second since the last character was transmitted.

General log only system errors

Errors 80 through 89 are general system errors. They are logged only; they do not cause the system to crash.

80 Grade 1 Front Preset Overrun

This indicates that the delivery on the Grade 1 Front hose did not stop at the preset or allocation limit. When this happens, the cutover point at which slow flow is entered automatically adjusts to compensate.

Note the difference from the encoder run-on error: encoder run-on is a continued flow after the end of delivery state has been reached, whereas preset overrun indicates that the end of delivery state was not reached in time to prevent excess fuel being delivered.

81 Grade 1 Rear Preset Overrun

This indicates that the delivery on the Grade 1 Rear hose did not stop at the preset or allocation limit.

82 Grade 2 Front Preset Overrun

This overrun error indicates that the delivery on the Grade 2 Front hose did not stop at the preset or allocation limit.

83 Grade 2 Rear Preset Overrun

Error 83 indicates that the delivery on the Grade 2 Rear hose did not stop at the preset or allocation limit.

84 Grade 3 Front Preset Overrun

This indicates that the delivery on the Grade 3 Front hose did not stop at the preset or allocation limit.

85 Grade 3 Rear Preset Overrun

This indicates that the delivery on the Grade 3 Rear hose did not stop at the preset or allocation limit.

86 Lost Reply (Console)

A Lost Reply error indicates that the pump comms are trying to reply to a poll from the Console, but did not succeed in sending a reply within 4 clock ticks (0.08s) of receiving the poll message. This means that the main loop tasks (other than comms) are taking up too much processor time, so that the comms do not get serviced often enough.

87..99 Not used

These error codes are reserved.

<u>PEC Fuel Pump Fluid/Float Switch operation.</u> <u>in</u> <u>Apollo Dispensers</u>

Software required:

<u>LPG Apollo requires</u>: Input Processor Assy = VI 1.21S (or >) This also allows for Single Temperature Probe operation. Dip Switch # 2 @ SW3 set "ON"

Main Processor Assy = VA 2.30P (or >)

Apollo Std Petrol/Diesel Dispensers requires: Main Processor Assy = VA 2.30P (or >)

Hardware required:

<u>LPG requires</u> = Float Switch Assy. with Foam Extension added, & mounted as low as possible to base/floor of Underground Sump Enclosure. Dip Switch #2 @ SW3 set "ON"

<u>Apollo Std Petrol/Diesel Dispensers requires</u> = Float Switch Assy mounted as low as possible to base/floor of Underground Sump Enclosure (note: Link must be fitted @ position 10 on Display for Fluid operation)

Operation Description: (when Float is activated)

Dispenser with one side only operational (delivering)

Unused Side – Display shows "FLUId"

Side in uses – Dispenser shuts down immediately (including Valves & Motor) Display sit stationary showing

sale value.

Dispenser will begin to Beep after a period of 1 Min. if Nozzle in not returned then Beep

Once Nozzle is returned, Displays will then Flash until Nozzle is again removed, at this point Displays will then show word "FLUId"

Refer to Resetting below.

Dispenser with both sides operational (delivering) (when Float is activated)

Both sides stop delivering immediately with Displays stationary displaying delivery values @ point when delivery stopped.

Again Dispenser will start to Beep if Nozzles not returned within a Minute period.

Once Nozzle is returned, Displays with Flash until Nozzle is removed, Displays with then show "FLUId"

In both above cases Sale value remains on Console until sale is actioned/completed. Dispenser will also show on ng Off Line

Console as being Off Line

Dispenser Non operational (no delivery) (when Float is activated)

"FLUId will be displayed on both sides of Dispenser

Console Displays Dispenser as Off Line.

Refer to Resetting below.

Testing Float Switch Operation:

Testing can be conducted by manually lifting Float with wire Hook or similar. Display should show **FLUId** with Dispenser going into Fatal error (Shut Down) Dispenser will require a Power shut down for a period of **One Minute** to **Reset** Normal operation can then commence.

Resetting Dispenser Procedure

If **FLUId** is displayed @ Dispenser, Power to that unit should be immediately removed, with Isolating Switch locked out to avoid being turned back on accidentally. **Call Service Provider**

Sump Enclosure should then be checked, removing Fluid present & source of leak repaired

Reconnect Power for Operation, should not need to reprogram if back up Battery still connected.

If pump Beeps: Hang up Nozzle.

If Displays Flash: Lift Nozzle then return to display Error

If Pump Off Line: Check for Error @ Pump (see above)

file @ gme c:/docum/pec/apollo2/float-desc.doc 23/02/01 Update: 01/03/01 02/04/02

Apollo 2000 Set-up, Installation & Parts Manual



Safety Operation

In case of damage to your Dispenser or Pump, which creates a safety hazard the following procedures **Must** be followed.

A Turn Off Pump at Console then....

Isolate power to the Dispenser or Pump.

Using the remote control switch located on the main electrical supply board.

Lock switch if lock mechanism provided, or take measures to ensure isolator will not be turned on prior to the safety hazard being rectified

Isolate power to the Submersible Turbine Pump

by the remote control switch located on the main electrical supply board.

Lock switch if lock mechanism provided, or take measures to ensure isolator will not be turned on prior to the safety hazard being rectified

Note: The isolation of the Submersible Turbine Pump could affect other dispenser on the forecourt.

Call your site manager or company representative immediately for further information.

B Do Not Apply power to the Dispenser without a full service inspection.

If there is a fire or injury, call : Emergency Services.

Caution

Should the word "**FLUId**" appear in Display immediately implement part A & B of this section Refer page 06 of this Manual <u>Apollo 3000 Set Up Procedure Std. Fuel</u> paragraph 06 for details

Caution

This equipment contains components that can be damaged by Electrostatic Discharge. Should you ever need to service this equipment, you must follow full anti-static precautions. Prior to servicing, earth all equipment and wear an anti-static strap. Component must be transported in anti-static material.

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The information in this manual is subject to change without notice and should not be construed as a commitment by PEC. Fuel Pumps

PEC Fuel Pumps has taken great effort to verify the accuracy of this manual but assumes no responsibility for any technical inaccuracies or typographical errors.

File @ gme c:/pec/apollo/safety.doc Updated 23/02/01

Apollo Manual

Contents

Page 1	Contents
Page 2 -5	First & Second Stage Installation Specifications
Page 6	Front Door Assy Lay out & Parts Descriptions
Page 7	Rear Door Assy lay out & Parts Descriptions
Page 8	Head Cabinet Assy Internal lay out & parts Descriptions
Page 9	Sump & Module Lay out & Parts Descriptions
page 10	Sump Internal Lay out & Parts Description
page 11	Sump Internal Lay out & Parts Description Mk 11
Page 12	Nozzle Holster & Delivery Pipe Lay out & Parts Description
Page 13 -14	Apollo Unit Set Up Procedure (Programming)
Page 15	Pump Stack Test
Page 16	Hydraulic & Intrinsic Connection Lay out Diagram (New Zealand
Page 17	Hydraulic & Intrinsic Connection Lay out Diagram (Australia)
Page 18	Quick Set Up & Test Record
Page 19-28	Error Codes
Page29	Main Processor lay out Circuit
Page 30	PCB Dip Switch Position
Page 31	Wiring Connections AC Control & Power Supply
Page 32	Logic Box Connections
Page 33	Details of Feed Line into Hydraulic Enclosure
Page 34	Hose Assy Specifications (Also refer pg. 9-11)
Page 35	Display Cable Layout

<u>Note</u>

This is an Interim Manual intended to cover Apollo trial sites, and will be reviewed once trials are complete and design is finalised.

Note also that the Apollo units are base on PEC standards 1000 & 8000 Dispensers and therefore this manual should be used in conjunction with PEC Modular Pumps Installation & Service Manual 87386

First Issued 06/08/98 updated 08/09/98 15/09/98 06/05/99 10/02/00 File @ gme c:/pec/apollo/intal1.doc

<u>BP Special Version Dispenser</u> <u>Supply & Installation Procedure</u>

Updated 24/06/98 / 21/07/98 / 30/04/99 05/05/99 File @ GME c:/pec/apollo/instal1.doc

PEC will supply required Components to site.

Components include;

Sump Box with Delivery Ducts & Internal Delivery Pipe Assys

fitted

Sump Box Lid Bulkhead Seals Sump Box Lid with Handles Sump Cover & Sub-frame with divider skirt fitted Main Wiring Looms & Junction Box (fitted into Sump Box) Cable Feed Flexible Conducts (40 & 50 mm Dia) with Fittings

Stage 1 - Installation Procedure

• Install Sump Box into position below ground level as shown



• Centralise Sump, with Box end Face to Column Face at a distance of 300mm



- Secure Cable feed Flexible Conduit to Sump Box (if not already fitted) (Later version one piece fixed Cable Duct)
- Install Internal Delivery Pipe Assys into ducting (if not already fitted)
- Plug or cover Delivery Ducts to stop foreign matter entering

Stage 1 - Installation Procedure continued

- Install Main Feed Lines Into Sump (refer Pg. 16 NZ & Pg. 17 Aus.) for correct positioning etc. (Refer page 33 for Feed Line Details)
 - T connector terminated with ³/₄ Ball Valve & ³/₄ -3/₄ BSP Elbow B22 22 12 12
 - Ensure Ball Valves Face toward BOTTOM of Sump, lever side towards Column
 - Check & tighten all Seals
 - Check for Leaks
- Recheck Sump position in relation to Column & Forecourt Surface as per Pg. 2
- Secure Delivery Ducts & Main Feed Lines into proposed Position
- Temporarily pack internal side walls of Sump using timber or similar to eliminate walls collapsing inwards during back filling
- Backfill with Sand to cover Feed Lines & secure Sump position
- Secure Mains & Data Cable Flex Conduits to Column to avoid movement
- Position & Secure Sump Lid Frame (Centralise around Sump Box) check with Forecourt Level
- Recheck Seals & Sump Position
- Back fill with sand to within 150mm of Forecourt Surface Level 30 50 mm up Skirting walls
- Concrete Forecourt Surface

Stage 2 - <u>Installation Procedure Modules & Delivery Pipe Assys</u> Components Supplied

Front & Rear Vertical Pipe Assys Head Cabinet Assy Hydraulic Module Assy (Addresses pre-set) & with Data Cables fitted Flexible Safety Hose Assys x 6 Internal Supply Line Hose Assys x 2 Sets Internal Delivery Hose Assys x 3

• Temporally fix Vertical Pipe & Holster Assy to Column in approx. position. Front Assy 89790 with top angle section pointing out to left from front view & Rear Assy 89791 pointing out to right as viewed from rear. (Note Fig. below viewed as front) 930 mm underside of Nozzle Holster Panel to Forecourt level (see Fig below) (Use Rope, Ratchet Tie or Bungy Cord).



- Fit Safety Flex Hose Assys to Delivery Pipe Assys (in Conduit) & Vertical Pipe 89790 & 89791
- Centralise & position Vertical Pipe Assys on Column
- Permanently attach Vertical Delivery Pipe Assys to Column with Bandit Strapping (See Fig for position) Options Drill & Screw Brackets to Column or use threaded draw rods (not supplied)
- Mount Logic Box to bracket on Vertical Pipe Assy under Head Cabinet
- Position & attach Head Cabinet to Column (hold temporarily with Ratchet Tie or similar) Fix permanently with Bandit Strapping. Option: Drill & Screw to Column
- (Bottom of Head Cabinet to be 1355mm from Forecourt Surface refer Fig above)
- Assemble External Hoses to Internal Delivery Pipe Assys in Ducting (Refer Pg.11) (Ensure Product Position is Correct Refer Pg. 16 or 17) **Hydraulic & Intrinsic**

Connections) or to Special Version eg. Sump on opersite side of Column.

- Attach Internal Feed Hose Assys x 3to Fixed Feed Lines in Sump
- (Ensure Product Position Is Correct)

Stage 2 - <u>Installation Procedure Modules & Delivery Pipe Assys</u> <u>Continues</u>

(Start with Module A closest to Column) (Refer Pg. 16 or 17)

- Install Module Assy. fit Hinge Pin lift module & Position Hold Up Brace (Refer pg. 9)
- Attach Feed Line & Delivery Lines to Meter Module

(Ensure Correct Feed Path - See Drawing Provided Pg. 16 or 17)

- Repeat previous procedure for the B Module then the C Module
- Connect Mains & Switched Phase Cables into AC Control Boxes (see Drawing Pg. 31) (Inspection required)
- Using Draw Cord Pull Encoder, Float Switch & AC Signal Cables through Cable
 Duct roll up & secure surplus cable
- Plug Cables into Logic PCB (see Drawing Pg. 32) Cables are Marked
- Fit Steel Wire Armoured Cable Mains Feed Line to Head Cabinet (Gland FLP.) connect as per Drawing Pg. 31 (inspection required) (Gland not Supplied)
- Insert Data Cable into Head Cabinet via Gland
- Insert Pump & LAN Comm's Cable into Head Cabinet & Connect

Pump Comms Refer Pg. 29 & 31 LAN Comms. Direct to FST unit (Plug Supplied)

- Install Earth Bonding Cable between Column & Head Cabinet
- Attach Nozzle Holster Switch Cables to Logic Box (see Drawing Pg. 32) + pg.16 & 17
- Check all Hydraulic & Electrical connections (Electricals to be Certified)
- Program Dispenser as per pages 13-18- (Also refer PEC Modular Pumps Manual 87372
- Test run checking for leaks etc.
- Check Cover is replaced over Power Supply PCB.



Refer Page 15 for Cabling Layout

Cable 87328 comes from Master Processor PCB to Right hand side (as viewed) of Preset Display 87281 Cable 87329 goes from left hand side of Main Display PCB 87276 (as viewed) to left hand side of Preset Display 87281 & then to top of the bottom Price Display 87271 Cable 87333 goes from bottom of Price Display 87271 to top of Price Display above it (repeats).

Apollo Door /Head Assy 89802 (Rear View) First issue 29/07/98



Display & Preset PCB's as per Front Door Assy Pg 6

Cable 87328 comes from Processor PCB 87102 & connects to right side of Preset PCB as viewed. Rear Display Cable 700mm centre connector comes form left hand side of Main Display 87276 to top connector of top Price Display 87271 & then to left hand connector of Preset Display 87281 as viewed.Cables 87333 goes from top connector of bottom Price Display 87271 to bottom connector of Price Display above it. (repeat)



Apollo Head Assy Internal First issued 29.07.98

Apollo Sump & Module Assy



Produce Feed Hose Assy - ³/₄ in Hose - ³/₄ Female/Female Sw/nut - 1.050 m ³/₄ (Feed Line to Module) x 3

Product Delivery Hose Assy -3/4 in Hose- 3/4 Female/Female Sw/Nut as below

"A" Module Hose = 0.9 m x 1 ("A/F" 1 with $\frac{3}{4}$ F. Sw/Nut -3/4 Male) Mk11 "A" Hose = 0.9 m x 2

- "B" Module Hose = 1.1 m x 2 Mk 11 "B" Hose = 1.39 m x 2
- "C" Module Hose = 1.46 m x 2 Mk 11 "C' Hose = 1.67 m x 2

Inside Sump



Bulkhead Seals for Product Feed line & Internal Delivery Pipes are fitted at PEC as part of original Sump assy. Specifications for these can be obtained on request.

Refer Page ?? for Mk11 Version



Mk 11 Inside Enclosure

Delivery Hose Lengths

89742 A/F&R = $\frac{3}{4}$ Hose @ 0.9m - $\frac{3}{4}$ Swivel Nut 19243/12/12/AU - F/Swivel 90 Elbow 1B243-12-12

89743 B/F&R = $\frac{3}{4}$ Hose @ 1.39m - $\frac{3}{4}$ Swivel Nut 19243/12/12/AU - F/Swivel 90 Elbow 1B243-12-12

89744 C/F&R = ³/₄ Hose @ 1.67m - ³/₄ Swivel Nut 19243/12/12/AU - F/Swivel 90 Elbow 1B243-12-12

Internal Supply Hose Lengths

89748 ³/₄ Hose @ 1.05m - ³/₄ Swivel Nut 19243/12/12/AU (x3)

<u>Pipe Assys are as follows:</u>

"A" = 89794 Internal Pipe Assy Upper

"B" = 89796 Internal Pipe Assy Middle

"C" = 89798 Internal Pipe Assy Lower

Note These pipe assys run up inside Ducting to connect to Vertical Pipe Assys attached to Column

Nozzle Holster & Delivery Pipe Assy



12.

Apollo Set Up Procedure Standard Fuel

1. Set Up Addresses Dip Switches

Set addresses on AC Control PCB as shown in table below

Note AC Control Boxes number from Left to right as viewed with Column on your left, refer

Apollo Hydraulic & Intrinsic Connections layout Section Pg. 16 & 17

Dip	Swit	ches	
4	3	2	1
on	on	on	off
on	on	off	on
on	on	off	off
	Dip 4 on on on	Dip Switt43onononononononon	Dip Switches432onononononononononononon

2. Preset Display PCB Dip Switch Setting (Ref. Pg. 30 Factory Preset)

3 Product front = 3,5 & 12 are on rest are off

3 Product rear = all set off

3. Power up

Apply Power, listen for long beep followed by five short beeps.

For Software Version VA 2.21 & > listen for single beep -pause-single- followed by six short

beeps

Displays should show as follows

I KOIVI	En	En U
	гп	 гп

Note if you get FUEL OFF then toggle Managers Switch to get required display.

4. Setting Hoses Active.

Empty RAM by pressing Diagnostic switch and enter 10-Fill-Fill (Note This operation not required for Software versions later than 2.21)

Activate as follows.

Hose $R1 = Enter 23$ -Fill-1-Fill
Hose R2 = Enter 43-Fill-1-Fill
Hose R3 = Enter 63-Fill-1-Fill

5. Check Pricing Displays read as indicated on Graphic Panel

Cents per Litre = "000.0" for Cents & Dollars per Litre = 0.000 for Dollars

Refer PEC Manual 87372 section "Dip Switch Settings Multipec" for corrections

Set Product Price

Product A = Enter 31-Fill-\$ amount(eg 0.86)-Fill

Product B = Enter 51-Fill-\$ amount-Fill

Product C = Enter 71-Fill-\$ amount-Fill

Note To test Comms. And Console control is working correctly, enter a non real price for each product and then switch unit over to Console control price should then change as set on console. Check both sides

7. Pump Number (Comms. Connection)

To connect to Console unit has to be numbered both front & rear.

To number Front Enter 20-Fill display = PF-00

Enter (#) display = PF- (number entered)- enter Fill

To number Rear Enter 21-Fill display = PF-00

Enter (#) display = PF- (number entered)- enter Fill Switch Managers Switch to normal

Note (#) = Pump/Console number

Note To switch Dispenser to LOCAL mode (Non Console control)

With Managers Key on Enter 04-Fill middle display shows LOCAL enter Fill again Switch Managers Switch to normal and wait 1 Minute

8. Plug in Battery

9. Test (Diagnostics)

Refer Pg.15

This test cheeks the operation of the pump motors (internal or submersible). The motor can be switched on and off, as can the slow and fast flow rates. The flow rate is displayed in the *Price per litre* display.

Pump motor Func	tion number
F1 & R1	30
F2 & R2	50
F3 & R3	70

Initially, the display appears as shown in the illustration. Decimal points between each set of two figures indicate whether nozzles switches are open. A central decimal point indicates air in the flow detected by the air sensor (if installed). The first digit gives the rate of flow for the hose, in tens of litres per minute, and the second digit counts the number of encoder errors received.



Note Encoder errors can be any number but must not change (eg change indicates error)

Diagnostic Testing of Motor & Valve Operation

This function can be used to turn Motor, Final & main stages of Solenoid valves idea for checking connection and correct operation etc.

Note Managers Switch must be on to access these functions & Diagnostic Switch pressed

- Function30 for Product'A'Function50 for Product'B'
- Function 70 for Product 'C'

Once in any of the above Function press key once as listed below to activate and a second time to deactivate. Note Numbers being activated show in 'Dollars Display"

Function
Motor
Sol/Valve final stage (front)
Sol/Valve main stage (front)
Sol/Valve final stage (rear)
Sol/Valve main stage (rear)

Apollo Hydraulic & Intrinsic Connections New Zealand

GME 05/06/98 up date 6/8/9, 15/09/98, 05/05/99, 10/02/00, 25/03/01 File @ GME

c:/mydrawdt/apollo/lay-out.idw (Pg 1)

Rear



Apollo Hydraulic & Intrinsic Connections Australia

GME 05/06/98 up date 6/8/98, 15/09/98, 05/05/99, 10/02/00, 25/03/01 File @ GME c:/mydrawdt/apollo/lay-out.idw(Pg 5)



Errors

This chapter contains the full list of error codes, in numerical order.

Errors are normally indicated by the error code (number) being displayed. The error is displayed as **ERRxx**, where **xx** is the code number. Errors are also written to an error log. You can check logged errors using Function 02 as detailed in chapter 4.

Startup System Errors

Error codes (01..09) are reserved for startup errors. This type of error is detected before the displays are initialised, and is reported using beep codes (pump beeps once for error 01, twice for error 02, etc.)

Some of these codes can also be dynamically checked during normal operation, in which case they will be reported in the normal way (i.e., they will display the **ERR xx** message and stop all deliveries).

These errors are fatal errors (processor halted) and require the pump to be reset. Power down and wait for 5 seconds before switching on the pump.

00 Start up log

This is not really an error it contains the number of startups.

01 Processor Error

This is a sequential IRAM address test which is performed at startup. It tests the processor's 4 register banks, and halts the processor if an error is found. This check is performed in the **init** module.

02 Internal Ram error

Error 02 is a sequential IRAM address test which is performed at startup. It covers all IRAM excluding the 4 register banks, and halts the processor if an error is found. This check is performed in the **init** module.

03 Eprom Error

Error 03 indicates a checksum error. This may occur either at startup or dynamically during operation. In either case the processor is halted if an error is found.

04 External RAM Error

This is a walking bit test of the XRAM. This test is performed both at startup (entire XRAM checked) and dynamically (one address per call from main loop). In either case the processor is halted if an error is found.

05 Non Volatile Setup

Error 05 is a check of the non volatile variables. These are the set up variables which must remain unchanged during a power failure. They remain constant unless changed by a diagnostic function. They are checked (against their backup variables) both at startup (all non-vol variables checked) and dynamically (one byte checked each call from main loop). If an error is found, the non volatile variables are all reset to their default values and (if not found during startup) the system restarts.

06 Delivery variables lost

This is a startup check of the current/last delivery related variables. These variables are overwritten with each new delivery, but in case of power loss, must be present between deliveries. Unlike the non-vol variables, during deliveries, these are continually changing and are therefore not checked dynamically. At startup, these are checked (for corruption of XRAM during power loss) against their backup variables. If an error is found, the non volatile variables are all reset to their default values.

07 Keyboard Error

This is a startup check of local or remote (input processor) DIP switch setting validity, and for the presence of the relevant keyboards. This error is non-fatal error which serves as an audible warning to reconfigure DIP switches or replace keyboards and restart the system.

08..09 Not used

Errors 08 and 09 are reserved.

Fatal Errors (excluding fatal startup errors)

Errors 10 through to 29 all cause the processor to stop. The errors are displayed but beeps are not sounded. The pump must be reset after one of these errors.

1

1015	Pump Control	State Errors (Pump AF)
		This indicates an attempt to enter an undefined side control state on a particular pump number.
16	Stack Error	
		The stack is continuously checked. If a stack overflow occurs, error 16 will be displayed. This check is performed in the dynchk module.
17 Di	splay Error	
		If a Display error is indicated, a translation error occurred when writing to one of the 7 segment LCD displays.
18	Variable Range	Error
		Error 18 indicates a global software parameter (ie pump, grade or price etc) is not within its normal range. This can be a result of corruption of the internal data RAM, which may cause unpredictable results.
		This check is not limited to any particular module, but is used by any procedure that requires range checking.
19	Dollar Maths Er	ror
		At the end of a delivery, the delivery dollar calculations are performed (ie price per litre multiplied by litres equals dollars). Error 19 indicates an error occurred in the calculations. A likely cause for this would be a price change (or corruption of the price variable) during a delivery.
20	Litres Maths Er	ror
		At the end of a delivery, the delivery quantity accumulation calculation is made (ie, total number of encoder counts for the delivery time multiplied by the encoder constant equals the litres displayed). Error 20 indicates an error occurred in the accumulation. If this is not the case, it is probable that the encoder is going too fast, such that the incoming encoder counts (which are accumulated under interrupt control) are not being "consumed" quickly enough by the maths routines to prevent a rollover.
21	Clock Error	
		A Clock Error indicates that the current time variable (which is used to time tag events) is not incrementing.
22	Motor Control I	Error
		Error 22 indicates that an attempt was made to turn a motor on or off when it was already in that state (according to the software).

23 Solenoid Control Error

This indicates that an attempt was made to open or close a solenoid valve when it was already in that state (according to the software). It will also occur (except in diagnostic mode) if an attempt is made to turn on a solenoid valve when the corresponding motor is not on.

24 Power Fail

This error indicates the system entered its main initialisation procedure (which should only happen on power up or as a result of certain diagnostic functions), but the power fail flag does not show power failed.

This may occur in the event of a total power loss (including the lithium battery) such that the XRAM was corrupted, or if the power fail procedures are not functioning correctly.

25 Input Processor to main failure

This error will occur if the system expects an Input Processor to be present (i.e., it was autodetected at power up) but is no longer receiving any comms response from it. This would be caused by either a fatal error in the input processor, or a physical loss of connection on the serial link between the two processor boards.

26 Main to Input Processor failure

This error will occur if the system expects an Input Processor to be present (i.e., it was autodetected at power up) and is receiving comms response from it, but the Input Processor is not receiving data from the main processor.

This would be caused by either a fatal error in the input processor, or a physical loss of connection on the serial link between the two processor boards.

27 Remote Parameters Failure

Error 27 will be displayed if the pump is not within the diagnostics functions and the remote rx_param block that was sent from the input microprocessor is different to the set stored by the you.

28 Display pointers corrupted

A constant check is dynamically made, of the display information. This error indicates an error has occurred which could cause incorrect information to be displayed on the LCDs.

29 Not used

These error codes are reserved.

Single Pump Number Fatal Errors

Errors 30 through to 59 do not cause a complete system crash, as they relate to a single pump number only. They cause the related pump to stop delivery, and its displays to flash. This continues until the nozzle is replaced and any nozzle on that pump number is removed again. The **ERRxx** message is then displayed on that pump number and all further processing of the pump ceases.

Note that all other pump numbers can continue unaffected. To use the affected pump again, the pump unit must be reset (powered off for at least 5 seconds).

30 LPG Temperature Probe 1 Error

This is caused by either an open circuit, short circuit or out of range error being detected on probe 1 by the input processor. This error is fatal only to the pump numbers associated with the LPG grade.

31 LPG Temperature Probe 2 Error

Error 31 is caused by either an open circuit, short circuit or out of range error being detected on probe 2 by the input processor. This error is fatal only to the pump numbers associated with the LPG grade.

Note Errors 32 – 37 apply to units fitted with software version lower than va 2.30p only

Units fitted with Software va 2.30p & greater & Float Switches fitted, Fatal Error as FLUId Ref. Pg 41
 32 Grade 1 Front hose Detected Fluid Present bottom of Hydraulic Sump Enclosure (Pump A1)

During a Grade 1 delivery, Float was activated for more than 1 minute.

33 Grade 1 Rear hose Detected Fluid Present bottom of Hydraulic Sump Enclosure (Pump B1)

During a Grade 1 delivery, Float was activated for more than 1 minute

34 Grade 2 Front hose Detected Fluid Present bottom of Hydraulic Sump Enclosure (Pump C2)

During a Grade 2 delivery, Float was activated for more than 1 minute.

35 Grade 2 Rear hose Detected Fluid Present bottom of Hydraulic Sump Enclosure (Pump D2)

During a Grade 2 delivery, Float was activated for more than 1 minute.

- 36 Grade 3 Front hose Detected Fluid Present bottom of Hydraulic Sump Enclosure (Pump E3)
- During a Grade 3 delivery, Float was activated for more than 1 minute
 Grade 3 Rear hose Detected Fluid Present bottom of Hydraulic Sump Enclosure (Pump F3)

During a Grade 3 delivery, Float was activated for more than 1 minute

38	Grade 1 Front encoder error (Pump A1)		
		Grade 1 front encoder inputs out of sequence for more than 1 count in 512 (0.19% minimum error	
20	Grado 1 Boar o	rate). This could be due to the encoder missing a count, the rotation being backwards, etc.	
39	(Pump B1)		
40		The Grade 1 rear encoder inputs were out of sequence.	
40	(Pump C2)	incoder error	
		Grade 2 front encoder inputs out of sequence for more than 1 count in 512 (0.19% minimum error rate). This could be due to the encoder missing a count, the rotation being backwards, etc.	
10	41 Grado 3 Eront o	Grade 2 Rear encoder error	
42	(Pump E3)	incoder error	
		The Grade 3 front encoder inputs were out of sequence.	
43	(Pump F3)	ncoder error	
		The Grade 3 rear encoder inputs were out of sequence.	
44	Grade 1 Front e (Pump A1)	encoder too fast	
		This error indicates an overflow of either encoder counts or encoder errors was detected for the Grade 1 front encoder.	
45	Grade 1 Rear ei (Pump B1)	ncoder too fast	
		There was an overflow of either encoder counts or encoder errors detected for the Grade 1 rear encoder	
46	Grade 2 Front e	encoder too fast	
	(Pump C2)		
		There was an overflow of either encoder counts or encoder errors detected for the Grade 2 front encoder.	
47	Grade 2 Rear ei (Pump D2)	ncoder too fast	
		There was an overflow of either encoder counts or encoder errors detected for the Grade 2 rear encoder.	
48	Grade 3 Front e	ncoder too fast	
	(Pump E3)		
		There was an overflow of either encoder counts or encoder errors detected for the Grade 3 front	

There was an overflow of either encoder counts or encoder errors detected for the Grade 3 front encoder.

49	Grade 3 Rear en (Pump F3)	coder too fast
		There was an overflow of either encoder counts or encoder errors detected for the Grade 3 rear encoder.
50	Grade 1 Front er (Pump A1)	ncoder run on
		Flow did not stop (the encoder was still rotating) at the end of a Grade 1 front hose delivery (i.e. after the "get dribble" state has timed out).
51	Grade 1 Rear en (Pump B1)	coder run on
52	Grade 2 Front er (Pump C2)	Flow did not stop (the encoder was still rotating) at the end of a Grade 1 rear hose delivery. ncoder run on
53	Grade 2 Rear en (Pump D2)	Flow did not stop (the encoder was still rotating) at the end of a Grade 2 front hose delivery. coder run on
54	Grade 3 Front er (Pump E3)	Flow did not stop (the encoder was still rotating) at the end of a Grade 2 rear hose delivery. ncoder run on
55	Grade 3 Rear en (Pump F3)	Flow did not stop (the encoder was still rotating) at the end of a Grade 3 front hose delivery. coder run on
56	LPG Overspeed	Flow did not stop (the encoder was still rotating) at the end of a Grade 3 rear hose delivery.
57	Loss of encoder	Flow rate detected during delivery exceeded overspeed trip setting. Note that this error on one LPG pump will display on both, regardless of whether the other is delivering or not.
		One of these values is corrupt, and has not yet been set back to a valid value (using the appropriate diagnostic function).
58	LPG Sensor fail	ure
		The LPG sensor has stopped providing or is providing incorrect information, to the input processor.
59	LPG system vap	oour present
	-	During an LPG delivery vapour was sensed in the system for more than one minute.

Non Fatal System Errors

Errors 60 through to 89 do not cause any loss of system functionality. They are logged only (for service use).

Comms Channel A errors

60 Channel A Receiver Parity Error

This indicates a parity error was detected in one or more of the received message bytes.

61 Channel A Receiver Framing Error

Character was received for which no stop bit was detected.

62 Channel A Receiver Break Error

A steady low (space) signal has appeared at a receiver, indicating a break condition at the transmitting end, causing this error code. The formal definition is that an all zero character with no stop bit has been received.

63 Channel A Receiver Overrun Error

This indicates an overflow of the 3 byte FIFO buffer for a receiving channel. This means that the processor is not reading the incoming data fast enough to prevent overwriting this stack.

64 Channel A Receiver Checksum Error

This error indicates the message received had a checksum error.

65 Channel A Receiver Data Error

Error 65 indicates the polling message received from the Console is an invalid type, i.e., a new feature has been added to a console which is not yet supported, or the comms line has been corrupted (in which case a checksum error will probably also occur).

66 Channel A Receiver Overflow Error

The message received was too long for the buffer, causing this error. This may happen if no EOM character or sequence is detected.

67 Channel A Transmitter Overflow Error

The transmitter has tried to send a message which is too long. This means that the transmit buffer's last position was reached, but an EOM character or sequence was not present.

68 Channel A Receive Timeout Error

This indicates that the receiver is expecting a character from the Console, but has not received one for more than 1 second.

69 Channel A Transmit Timeout Error

This timeout error indicates that the transmitter is attempting to send a message to the Console, but there has been a delay of more than 1 second since the last character was transmitted.
Comms Channel B errors

70 Channel B Receiver Parity Error

Error 70 indicates a parity error was detected in one or more of the received message bytes.

71 Channel B Receiver Framing Error

A character was received for which no stop bit was detected.

72 Channel B Receiver Break Error

A steady low (space) signal has appeared at a receiver, indicating a break condition at the transmitting end. The formal definition is that an all zero character with no stop bit has been received.

73 Channel B Receiver Overrun Error

This indicates an overflow of the 3 byte FIFO buffer for a receiving channel. This means that the processor is not reading the incoming data fast enough to prevent overwriting this stack.

74 Channel B Receiver Checksum Error

The message received had a checksum error.

75 Channel B Receiver Data Error

This indicates that the polling message received from the Input Processor is an invalid type (or that the comms line has been corrupted, in which case a checksum error will probably also occur).

76 Channel B Receiver Overflow Error

The message received was too long for the buffer. This may happen if no EOM character or sequence is detected.

77 Channel B Transmitter Overflow Error

The transmitter has tried to send a message which is too long. This means that the transmit buffer's last position was reached, but an EOM character or sequence was not present.

78 Channel B Receive Timeout Error

This indicates that the receiver is expecting a character from the Input Processor, but has not received one for more than 1 second.

79 Channel B Transmit Timeout Error

This indicates that the transmitter is attempting to send a message to the Input Processor, but there has been a delay of greater than 1 second since the last character was transmitted.

General log only system errors

Errors 80 through 89 are general system errors. They are logged only; they do not cause the system to crash.

80 Grade 1 Front Preset Overrun

This indicates that the delivery on the Grade 1 Front hose did not stop at the preset or allocation limit. When this happens, the cutover point at which slow flow is entered automatically adjusts to compensate.

Note the difference from the encoder run-on error: encoder run-on is a continued flow after the end of delivery state has been reached, whereas preset overrun indicates that the end of delivery state was not reached in time to prevent excess fuel being delivered.

81 Grade 1 Rear Preset Overrun

This indicates that the delivery on the Grade 1 Rear hose did not stop at the preset or allocation limit.

82 Grade 2 Front Preset Overrun

This overrun error indicates that the delivery on the Grade 2 Front hose did not stop at the preset or allocation limit.

83 Grade 2 Rear Preset Overrun

Error 83 indicates that the delivery on the Grade 2 Rear hose did not stop at the preset or allocation limit.

84 Grade 3 Front Preset Overrun

This indicates that the delivery on the Grade 3 Front hose did not stop at the preset or allocation limit.

85 Grade 3 Rear Preset Overrun

This indicates that the delivery on the Grade 3 Rear hose did not stop at the preset or allocation limit.

86 Lost Reply (Console)

A Lost Reply error indicates that the pump comms are trying to reply to a poll from the Console, but did not succeed in sending a reply within 4 clock ticks (0.08s) of receiving the poll message. This means that the main loop tasks (other than comms) are taking up too much processor time, so that the comms do not get serviced often enough.

87..99 Not used

These error codes are reserved.

Main Processor Board

Information & Connections Part Number 87101

The main Processor Board controls all Pump operations, either alone or together with an input Processor Board The basic elements are :

80c31 or 80c32 Processor 64K external program Memory (Eprom) 32K Static Ram (Battery backed 2692 DUART Encoder Interface Power Control Display I/O Interface External / Internal program Selection Diagnostic communications AC Control Pump Communications Interface Auxiliary I/O



Main processor connections

Display Dip Switch Location on Front Preset Display PCB Assy





Control Logic Distribution PCB Assy 87110



Feed Line Detail



Note distance between test point seals on assy. shown above must be min possible . Inside distance between Bulkhead Seals in Hydraulic Enclosure is, 0.432m therefore feed line Tee termination arrangement must fit within this distance.



Above view is as viewed from enclosure (sump) end away from Column (RH end). Tee & Shut off Valve hang down towards floor of enclosure with ³/₄ Elbow facing to back face of enclosure. Handle of shutoff valve operates in the same plan as feed line, (eg front to rear.

GME 15/09/98 Up date 27/03/01 File @ GME c:/ mydrawdt/apollo/lay-out.idw Pg. hose spec (Pg 3)

External Hose Assy Specifications

 Above Bry Break Note 1 per each external hose:
 5/8 ID Hose @ 250 mm 7/8 SAE Sw/Nut (824170)- 3/4 BSPP Fittings

 Hose Assy "A" :
 5/8 ID Hose @ 3.15 m
 3/4 BSPP (01805) - 3/4 BSP Female (01803) Fittings

 Hose Assy "B":
 5/8 ID Hose @ 3.3 m
 3/4 BSPP (01805) - 3/4 BSP Female (01803) Fittings

 Hose Assy "C":
 5/8 ID Hose @ 3.5 m
 3/4 BSPP (01805) - 3/4 BSP Female (01803) Fittings

 3/4 BSPP (01805) - 3/4 BSP Female (01803) Fittings
 3/4 BSPP (01805) - 3/4 BSP Female (01803) Fittings

Internal Hose Assy Specifications

Product Feed Hose Assy: - 3/4 ID Hose @ 1.05 m - 3/4 BSP Female Sw/Nut both ends (3 per unit) (Feed Line to Modules) Safety Hose Assy. Pt. # 89740 Cut hose @ 250mm Fittings as above

Product Delivery Hose Assy - 3/4 ID Hose - 3/4 Female Swivel Nut fittings both ends (see A/F option) "A" Module : @ 0.9 m x 1 Note " A/F" : 1 x 3/4 Hose @ 0.9 m - 3/4 Female S/Nut - 3/4 BSPT Male fitting) "B" Module : @ 1.1 m x 2 "C" Module : @ 1.46 m x 2

Internal Hose Assy Specifications Mk11

Product Delivery Hose Assy - 3/4 ID Hose - 3/4 Female Swivel Nut 19243/12/12/AU & 3/4 F/Swivel 90 Elbow 1B243-12-12 Hose cut as below

"A" Module : 89742 @ 0.9 m x 2

"B" Module : 89743 @ 1.39 m x 2

"C" Module : 89744 @ 1.67 m x 2



File @ GME c:/mydrawdt/draw/apollo/display.idw